

Challenges in Inverse Modeling and Data Assimilation of Atmospheric Constituents

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Our goal is to combine observations and models to improve our estimate of the state (constituents) of a system (atmosphere).



Our goal is to combine observations and models to improve our estimate of the sources (of constituents) in the system (atmosphere).

from a Bayesian framework: (source given observations of the state) α (observations given the source) (source)

 $\begin{bmatrix} x & | & Y \end{bmatrix} & \alpha & \begin{bmatrix} Y & | & x \end{bmatrix} \\ (\text{posterior}) & \alpha & (\text{likelihood}) & (\text{prior}) \\ \end{bmatrix}$

our model of the system



from a 4km WRF-Chem North American Monsoon (NAM) Simulation (~July/Aug 2006) P.I.s Mary Barth/Alma Hodzic http://acd.ucar.edu/~barthm/namcase.html

processes $\frac{\partial d}{\partial t} = \left(\frac{\partial d}{\partial t}\right)_{\text{transport}} + \left(\frac{\partial d}{\partial t}\right)$ emissions $+\left(\frac{\partial [CO]}{dt}\right)_{chemistry} + \left(\frac{\partial [CO]}{dt}\right)_{chemistry}$ ^Jdevosition $-k_{CO-OH}[CO][OH]$

 $k_{CH_4-OH}[CH_4][OH]$

observations of the system

In-Situ Measurements



Remote-sensed Measurements



e.g. Terra MOPITT, Aura TES, Envisat SCIAMACHY, Aqua AIRS, Aura MLS, ACE FTS, Metop IASI

ESP

Source Inventories

Ancillary Data

Fire Data

Aircraft Measurements





observation and model

DA problem

observation = h(state) + error

$$\mathbf{Y} = \mathbf{h} (\mathbf{x}) + \boldsymbol{\varepsilon}$$
 with $\boldsymbol{\varepsilon} \sim N(\mathbf{0}, \mathbf{R})$
 $\mathbf{Y} = \mathbf{H}\mathbf{x} + \boldsymbol{\varepsilon}$ linear case

In the case of direct observations of CO, ${\bf H}$ is simply a linear interpolation of the model CO state to the observation

However, in the case of remote-sensed measurements of CO, \mathbf{H} can be more complicated (may not be non-linear too!). For example,

 $y_{radiance} = h(x) + e_y \;$ where $h\left(\; \right)$ can be a radiative transfer model (RTM)

 $\mathbf{y}_{radiance} = \frac{\delta \mathbf{y}}{\delta \mathbf{x}} \mathbf{x} + \mathbf{e}_{y} \text{ linear case where } \frac{\delta \mathbf{y}}{\delta \mathbf{x}} \text{ is the measurement sensitivity}$ $\mathbf{y}_{retrieval} = \hat{\mathbf{x}} = \mathbf{x}_{a} + \frac{\delta \hat{\mathbf{x}}}{\delta \mathbf{x}} (\mathbf{x} - \mathbf{x}_{a}) + \mathbf{e}_{x} \text{ where } \mathbf{A} = \frac{\delta \hat{\mathbf{x}}}{\delta \mathbf{x}} \text{ is the averaging kernel}$



Inverse problemobservation = h(source) + error $Y = h(x) + \varepsilon$ with $\varepsilon \sim N(0, R)$ $Y = Hx + \varepsilon$ linear case

In the case of direct observations of CO, \mathbf{H} is matrix of response functions (mapping the source to the state) + a linear interpolation of the model CO state to the observation

However, in the case of remote-sensed measurements of CO, H can be more complicated (may not be non-linear too!). For example, $y_{radiance} = h(x) + e_y$ where h() can be a radiative transfer model (RTM)

 $\mathbf{y}_{\text{radiance}} = \frac{\delta \mathbf{y}}{\delta \mathbf{x}} \mathbf{x} + \mathbf{e}_{y} \quad \text{linear case where } \frac{\delta \mathbf{y}}{\delta \mathbf{x}} \text{ is the measurement sensitivity}$ $\mathbf{y}_{\text{retrieval}} = \hat{\mathbf{x}} = \mathbf{x}_{a} + \frac{\delta \hat{\mathbf{x}}}{\delta \mathbf{x}} (\mathbf{x} - \mathbf{x}_{a}) + \mathbf{e}_{x} \quad \text{where } \mathbf{A} = \frac{\delta \hat{\mathbf{x}}}{\delta \mathbf{x}} \quad \text{is the averaging kernel}$





$\begin{bmatrix} x & | & Y \end{bmatrix}$ $\begin{bmatrix} Y & | & x \end{bmatrix}$ $\begin{bmatrix} x &] \\ (posterior)$ (likelihood) (prior)

is $N(\mathbf{x}^{f}, \mathbf{P}^{f})$ and $\mathbf{Y} = \mathbf{H}\mathbf{x} + \varepsilon$ with $\varepsilon \sim N(0, \mathbf{R})$, the posterior is $N(\mathbf{x}^{a}, \mathbf{P}^{a})$

$$J_{x} = (y - Hx^{f})^{t}R^{-1}(y - Hx^{f}) + (x - x^{f})^{t}P^{f^{-1}}(x - x^{f})$$

An estimate \mathbf{x}^{a} of the state can be expressed as: $x^{a} = \left(H^{t}R^{-1}H + P^{f^{-1}}\right)^{-1} \left(H^{t}R^{-1}y + P^{f^{-1}}x^{f}\right), P^{a} = \left(H^{t}R^{-1}H + P^{f^{-1}}\right)^{-1}$

Kalman Filter

$$x^{a} = x^{f} + K(y - Hx^{f}), \quad P^{a} = (I - KH)P^{f}$$
$$x^{a} = x^{f} + P^{f}H^{t}(HP^{f}H^{t} + R)^{-1}(y - Hx^{f})$$

Can be recast as:

$$x^{a} = x^{f} + P^{f}H^{t}(HP^{f}H^{t})^{-1} (HP^{f}H^{t})(HP^{f}H^{t} + R)^{-1}(y - Hx^{f})$$

least-squares shrink to Hx^{f}



e.g. [emission | MOPITT] ~ [MOPITT | emission] [emission] $N(\mathbf{x}^{a}, \mathbf{P}^{a})$ $N(\mathbf{H}\mathbf{x}, \mathbf{R})$ $N(\mathbf{x}^{f}, \mathbf{P}^{f})$

We solve for regional source scaling factors

e.g.



Note that the posterior mean is sensitive to data, prior estimates, error specification and model leading to persistent discrepancies in source estimates

(No TransCom framework for CO)





Sensitivity Tests of Error Assumptions and Obs Data Choice



Heald et al. (2004)



Sensitivity Tests of Error Assumptions and Obs Data Choice



Arellano et al. (2004)



RESP

Comparison between Adjoint and Analytical Solution



adjoint inversion

Kopacz et al. (2009)

sensitivity to observing network

Top-down Estimates of Black Carbon



PCRESP



Hu et al. (2009)

sensitivity to GCTM transport

CRESP

differences in response functions differences in inverse results





Arellano and Hess, (2006)

recent top-down estimates of CO sources

annual estimates of scaling factors

RESP



Kopacz et al., (2010)



recent top-down estimates of CO sources



Kopacz et al., (2010)



recent top-down estimates of CO sources



Kopacz et al., (2010)





posterior CO still exhibit large biases



Kopacz et al., (2010)

problems?

posterior CO still exhibit large biases



RESP









Heald et al. (2004)



1) Inversions with a regional focus

- reconciling differences in inverse results
- reducing aggregation errors

2) TransCom-like CO experiments

- understanding errors in GCTM
- elucidating differences in methodology (perfect model experiments)

3) Towards a more integrated/synergistic approach

- multi-species/multi-platform inversions
- state/source estimation

4) Better error characterization

- observational errors (biases/inconsistencies)
- model errors
- emission errors







capability to evaluate the forecast model



error characterization using ensembles

Temperature Spread @ 500 hPa

RESP



CO Spread @ 500 hPa (ppbv)



U Wind Spread @ 500 hPa (m/s)





